



Edition 1.0 2024-07

TECHNICAL SPECIFICATION



Nanomanufacturing – Key control characteristics – Part 9-2: Nanomagnetic products – Magnetic field distribution: Magneto-optical indicator film technique

INTERNATIONAL ELECTROTECHNICAL COMMISSION

ICS 07.120

ISBN 978-2-8322-8987-7

Warning! Make sure that you obtained this publication from an authorized distributor.

CONTENTS

F	OREWORD.		7
IN	TRODUCTI	ON	9
1	Scope		11
2	Normative	e references	11
3	Terms an	d definitions	12
	3.1 Ger	eral terms	
		eral terms related to magnetic stray field characterization	
		ns related to the measurement method described in this document	
		ns related to the magneto optical indicator film (MOIF)	
		ns related to Faraday rotation	
	3.6 Terr	ns related to the magneto-optical measurement setup	19
	3.7 Teri	ns related to optical microscopy	21
	3.8 Terr	ns related to the setup calibration process	22
	3.9 Terr	ns related to the magneto-optical measurement process	23
	•	control characteristics measured according to this standard	
4	Symbols	and abbreviated terms	24
5	General .		25
	5.1 Mea	surement principle	25
	5.1.1	Overview	25
	5.1.2	Magneto-optical indicator films	26
	5.1.3	Sensor	27
	5.1.4	Faraday effect in reflection	28
	5.1.5	Measurement scheme	
	5.1.6	MOIF signal generation theory	
	5.1.7	MOIF measurement modes	
	5.1.8	Feature detection mode	
	5.1.9	Quantitative spatially resolved feature detection mode	
		cription of measurement equipment or apparatus	
	5.2.1	MOIF imaging system	
	5.2.2	MOIF imaging systems for spot measurements, confocal microscopy	
	5.2.3	Imaging systems in wide field geometry	
	5.2.4 5.2.5	MOIF signal detection MOIF signal detection schemes overview	
	5.2.5 5.2.6	MOIF signal detection by a polarizing filter as an analyser	
	5.2.0	Differential MOIF signal detection by a polarizing filter plus a Faraday	32
	J.Z.1	rotator to modulate the signal for lock-in detection	32
	5.2.8	MOIF signal generation by a polarization camera	
	5.2.9	MOIF signal generation theory for direct MOIF measurements	
	5.2.10	Selecting the analyser operating angle	33
	5.2.11	MOIF signal generation theory in differential MOIF measurements	34
	5.2.12	MOIF signal generation theory in the polarization measurement using a	
		polarization camera	
~		pient conditions during measurement	
6		nent procedure	
		bration of measurement equipment	36
	6.1.1	Calibration of analyser-based MOIF measurements for purely perpendicular magnetic fields $H = H$	26
		perpendicular magnetic fields $H = H_Z$	

7

6.1.2	Calibration approach for one pixel	36
6.1.3	Calibration approach for array sensors using an analyser-based detection scheme	37
6.1.4	Background image subtraction	37
6.1.5	Calibration of differential MOIF for perpendicular magnetic fields $H = H_Z$.	38
6.1.6	Calibration approach	38
6.1.7	Providing the perpendicular calibration field	39
6.2 M	OIF key control parameters	40
6.2.1	General	40
6.2.2	Calibrated external magnetic field, H_{Z}^{ext}	40
6.2.3	Intensity of the light source	40
6.2.4	Optical imaging geometry	40
6.2.5	Thickness of the MOIF, <i>d</i> ^{MOIF}	40
6.2.6	Measurement height, <i>h</i>	41
6.2.7	Sensor measurement temperature, <i>T</i> ^{sensor}	41
6.2.8	Environmental measurement temperature, <i>T</i> ^{env}	41
6.2.9	Scan size $Sx \times Sy$ and pixel resolution Nx , Ny and pixel size $\Delta x \times \Delta x$	41
6.3 D	etailed description of the measurement procedure	42
6.3.1	General	42
6.3.2	Sample mounting	42
6.3.3	Temperature stabilization	42
6.3.4	Frame averaging	42
6.3.5	Background image	
6.3.6	Raw data distribution	43
6.3.7	Measurement procedure for geometrical feature detection	43
6.3.8	Measurement procedure for calibrated magnetic field measurements (analyser based)	43
6.3.9	Detailed description of the MOIF calibration procedure for quantitative stray field measurements	44
6.3.10	Detailed description of the MOIF calibrated stray field measurement	
C 4 M	procedure	46
6.4 M	easurement accuracy Contribution of in-plane magnetic field components	
6.4.1 6.4.2		
	In-plane magnetic fields contribution for low magnetic fields $H \ll H_{uoop}$.	40
6.4.3	In-plane magnetic field contribution for fields in the order of magnitude of H_{uoop}	49
6.4.4	Forward simulation	49
6.4.5	Influence of the finite sensor thickness	49
6.4.6	Transfer function-based sensor thickness correction	50
6.4.7	Spatial resolution	50
6.4.8	Diffraction limited resolution	50
6.4.9	Sensor thickness limited resolution	50
6.4.10	Signal generation artefacts in MOIF measurements	51
6.4.11	Uncertainty evaluation	51
6.4.12	Calibration uncertainty	51
6.4.13	Uncertainty of calibrated field measurement	
Data ar	nalysis and interpretation of results	52
7.1 Q	uantitative data analysis	52

7.2	Secondary parameters from MOIF measurements	52
7.2.1	General	52
7.2.2	Secondary parameters of magnetic scales	52
7.2.3	Secondary parameters of grain-oriented electrical steel sheets	53
8 Resu	Its to be reported	53
8.1	Cover sheet	53
8.2	Product / sample identification	53
8.3	Measurement conditions	53
8.4	Measurement specific information (examples)	53
8.5	Measurement results	53
Annex A (informative) Supporting information	54
A.1	Mathematical basics	54
A.1.1	Continuous Fourier transform versus discrete Fourier transform	54
A.1.2	Partial (two-dimensional) Fourier space	54
A.1.3	Cross correlation theorem	55
A.2	Pseudo-Wiener filter	55
A.2.1	Pseudo-Wiener filter-based deconvolution process	55
A.2.2	L-curve criterion	55
A.3	Magnetic fields in partial Fourier space	55
A.3.1	Differentiation in partial Fourier space	55
A.3.2	Magnetic fields in partial Fourier space	56
A.4	Calculating the equilibrium magnetization of uniaxial in-plane MOIF sensors in external magnetic fields	56
A.4.1	Solving the free energy equation	56
A.4.2	Determination of the anisotropy constants of the sensor active material	58
A.4.3	Determination of the saturation magnetization at the MOIF active sensor material	60
A.5		
71.0	Impact of finite sensor thickness	60
A.5.1		
	Transfer function-based thickness correction	60
A.5.1	Transfer function-based thickness correction Estimation of the impact of the finite sensor thickness Measurement reliability and signal generation artefacts in MOIF	60 61
A.5.1 A.5.2	Transfer function-based thickness correction Estimation of the impact of the finite sensor thickness Measurement reliability and signal generation artefacts in MOIF measurements	60 61 61
A.5.1 A.5.2 A.6	Transfer function-based thickness correction Estimation of the impact of the finite sensor thickness Measurement reliability and signal generation artefacts in MOIF measurements Illumination inhomogeneity	60 61 61 61
A.5.1 A.5.2 A.6 A.6.1	Transfer function-based thickness correction Estimation of the impact of the finite sensor thickness Measurement reliability and signal generation artefacts in MOIF measurements Illumination inhomogeneity Residual intensities due to non-ideal optical setups, background signals	60 61 61 61 61
A.5.1 A.5.2 A.6 A.6.1 A.6.2	Transfer function-based thickness correction	60 61 61 61 61 62
A.5.1 A.5.2 A.6 A.6.1 A.6.2 A.6.3	Transfer function-based thickness correction	60 61 61 61 61 62 62
A.5.1 A.5.2 A.6 A.6.1 A.6.2 A.6.3 A.6.4	Transfer function-based thickness correction Estimation of the impact of the finite sensor thickness Measurement reliability and signal generation artefacts in MOIF measurements Illumination inhomogeneity Residual intensities due to non-ideal optical setups, background signals Nonlinearities of the sensors used as detection units Artefacts resulting from magnet units Artefacts resulting from sensor domain pattern	60 61 61 61 62 62 62
A.5.1 A.5.2 A.6 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5	Transfer function-based thickness correction Estimation of the impact of the finite sensor thickness Measurement reliability and signal generation artefacts in MOIF measurements Illumination inhomogeneity Residual intensities due to non-ideal optical setups, background signals Nonlinearities of the sensors used as detection units Artefacts resulting from magnet units Artefacts resulting from sensor domain pattern Driving the sensor in saturation	60 61 61 61 62 62 62 62
A.5.1 A.5.2 A.6 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5 A.6.6	Transfer function-based thickness correction Estimation of the impact of the finite sensor thickness Measurement reliability and signal generation artefacts in MOIF measurements Illumination inhomogeneity Residual intensities due to non-ideal optical setups, background signals Nonlinearities of the sensors used as detection units Artefacts resulting from magnet units Artefacts resulting from sensor domain pattern Driving the sensor in saturation Driving the detection unit in saturation Contingency strategy	60 61 61 61 62 62 62 62 62 62 63
A.5.1 A.5.2 A.6 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5 A.6.6 A.6.6 A.6.7 A.6.8 A.6.9	Transfer function-based thickness correction Estimation of the impact of the finite sensor thickness Measurement reliability and signal generation artefacts in MOIF measurements Illumination inhomogeneity Residual intensities due to non-ideal optical setups, background signals Nonlinearities of the sensors used as detection units Artefacts resulting from magnet units Artefacts resulting from sensor domain pattern Driving the sensor in saturation Driving the detection unit in saturation Contingency strategy Choice of adequate measurement conditions	60 61 61 61 62 62 62 62 62 63 63
A.5.1 A.5.2 A.6 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5 A.6.6 A.6.6 A.6.7 A.6.8 A.6.9	Transfer function-based thickness correction Estimation of the impact of the finite sensor thickness Measurement reliability and signal generation artefacts in MOIF measurements Illumination inhomogeneity Residual intensities due to non-ideal optical setups, background signals Nonlinearities of the sensors used as detection units Artefacts resulting from magnet units Artefacts resulting from sensor domain pattern Driving the sensor in saturation Driving the detection unit in saturation Contingency strategy Choice of adequate measurement conditions	60 61 61 61 62 62 62 62 62 63 63 64
A.5.1 A.5.2 A.6 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5 A.6.6 A.6.6 A.6.7 A.6.8 A.6.9	Transfer function-based thickness correction Estimation of the impact of the finite sensor thickness Measurement reliability and signal generation artefacts in MOIF measurements Illumination inhomogeneity Residual intensities due to non-ideal optical setups, background signals Nonlinearities of the sensors used as detection units Artefacts resulting from magnet units Artefacts resulting from sensor domain pattern Driving the sensor in saturation Driving the detection unit in saturation Contingency strategy Choice of adequate measurement conditions	60 61 61 61 62 62 62 62 62 63 63 64
A.5.1 A.5.2 A.6 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5 A.6.6 A.6.7 A.6.8 A.6.9 Annex B (Transfer function-based thickness correction	60 61 61 61 62 62 62 62 62 62 63 63 64 64 64
A.5.1 A.5.2 A.6 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5 A.6.6 A.6.7 A.6.8 A.6.9 Annex B (B.1 B.2 B.3	Transfer function-based thickness correction Estimation of the impact of the finite sensor thickness Measurement reliability and signal generation artefacts in MOIF measurements Illumination inhomogeneity Residual intensities due to non-ideal optical setups, background signals Nonlinearities of the sensors used as detection units Artefacts resulting from magnet units Artefacts resulting from sensor domain pattern Driving the sensor in saturation Driving the detection unit in saturation Contingency strategy Choice of adequate measurement conditions informative) Worked example for geometrical feature detection Measurement procedure and data analysis Test report	60 61 61 61 62 62 62 62 62 62 63 63 64 64 64
A.5.1 A.5.2 A.6 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5 A.6.6 A.6.7 A.6.8 A.6.9 A.6.9 A.6.9 A.6.9 A.6.9 A.6.9 A.6.9 A.6.9 A.6.9 A.6.1 A.6.2 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5 A.6.4 A.6.5 A.6.4 A.6.5 A.6.5 A.6.5 A.6.6 A.6.7 A.6.8 A.6.9 A.6.9 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5 A.6.4 A.6.5 A.6.4 A.6.5 A.6.4 A.6.5 A.6.4 A.6.5 A.6.4 A.6.5 A.6.4 A.6.5 A.6.6 A.6.5 A.6.6 A.6.5 A.6.6 A.6.7 A.6.8 A.6.9 A.6.9 A.6.9 A.6.7 A.6.9 B.1 B.3 B.3 B.3.1	Transfer function-based thickness correction Estimation of the impact of the finite sensor thickness Measurement reliability and signal generation artefacts in MOIF measurements Illumination inhomogeneity Residual intensities due to non-ideal optical setups, background signals Nonlinearities of the sensors used as detection units Artefacts resulting from magnet units Artefacts resulting from sensor domain pattern Driving the sensor in saturation Driving the detection unit in saturation Contingency strategy Choice of adequate measurement conditions informative) Worked example for geometrical feature detection Measurement procedure and data analysis Test report Cover sheet	60 61 61 61 62 62 62 62 62 62 63 63 64 64 64 64
A.5.1 A.5.2 A.6 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5 A.6.6 A.6.7 A.6.8 A.6.9 Annex B (B.1 B.2 B.3 B.3.1 B.3.1	Transfer function-based thickness correction Estimation of the impact of the finite sensor thickness Measurement reliability and signal generation artefacts in MOIF measurements Illumination inhomogeneity Residual intensities due to non-ideal optical setups, background signals Nonlinearities of the sensors used as detection units Artefacts resulting from magnet units Artefacts resulting from sensor domain pattern Driving the sensor in saturation Driving the detection unit in saturation Contingency strategy Choice of adequate measurement conditions informative) Worked example for geometrical feature detection Background. Measurement procedure and data analysis Test report Cover sheet General product description and procurement information	60 61 61 61 62 62 62 62 62 62 63 63 64 64 64 64 64
A.5.1 A.5.2 A.6 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5 A.6.6 A.6.7 A.6.8 A.6.9 A.6.9 A.6.9 A.6.9 A.6.9 A.6.9 A.6.9 A.6.9 A.6.9 A.6.1 A.6.2 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5 A.6.4 A.6.5 A.6.4 A.6.5 A.6.5 A.6.5 A.6.6 A.6.7 A.6.8 A.6.9 A.6.9 A.6.1 A.6.2 A.6.3 A.6.4 A.6.5 A.6.4 A.6.5 A.6.4 A.6.5 A.6.4 A.6.5 A.6.4 A.6.5 A.6.4 A.6.5 A.6.4 A.6.5 A.6.6 A.6.5 A.6.6 A.6.5 A.6.6 A.6.7 A.6.8 A.6.9 A.6.9 A.6.9 A.6.7 A.6.9 B.1 B.3 B.3 B.3.1	Transfer function-based thickness correction	60 61 61 62 62 62 62 62 62 63 63 64 64 64 64 64 64 64

B.3.5	KCC measurement results	65
Annex C (inf	ormative) Worked example for quantitative spatially resolved stray field	
measuremer	its	67
C.1 Ba	ackground	67
C.2 M	easurement procedure and data analysis	67
C.3 Te	est report	67
C.3.1	Cover sheet	67
C.3.2	General product description and procurement information	67
C.3.3	Measurement conditions	67
C.3.4	Measurement specific information	67
C.3.5	KCC measurement results	68
Bibliography		69
	ypical MOIF hysteresis curve and effective MOIF anisotropy field B_{A}	
Figure 2 – S	chematic of the functional layers of a MOIF sensor	27
Figure 3 – S	chematic MOIF setup	28
Figure 4 – In	naging geometries that can be used for MOIF imaging	31
-	OIF measurement schemes for detection of the Faraday rotation	
-	chematic representation of the impact of angle θ between analyser and	-
-	the relation between intensity <i>I</i> ^{det} at the detector and magnetic field in the	
	In the relation between intensity $T^{\mu\nu\nu}$ at the detector and magnetic neithin the state plane H_7	33
	xample of a calibration curve	
Figure 8 – A	ngle of rotation of the plane of polarization of MOIF magnetization vector	
under an ext	ernal magnetic field	38
Figure 9 – F	eld distribution of a 25 cm diameter pole shoe electromagnet at 19,8 mT	40
Figure 10 –	mpact of high in-plane components on the measured MOIF signal	49
Figure 11 –	Decay behaviour of H_{z} as a function of the pole width for magnetic scales	
	lic magnetic pole pattern	50
	Example of the results of an FMR characterization of a MOIF sensor	
-	Impact of finite MOIF thickness: wavelength λ dependent relative decay	
•		61
Figure A.3 -	Typical intensity versus magnetic field curve	62
-	Characteristic domain structure of grain-oriented electrical steel	
-	-	04
	Measurement results: Domain visualization via magneto-optical imaging: ous domain structure (initial state), b) to e) domain behaviour under	
	increasing external magnetic field parallel to the rolling direction, and	
f) after subse	equently switching off the field	66
	Calibrated stray field distribution at a distance of $h = 560 \ \mu m$ from the e magnetic scale	68
Figure C.2 -	The calibrated field distribution along a cross section of Figure C.1 at $y =$	
	derived positions of all zero crossings	68
	breviated terms	
Table 2 – Sy	mbols	25
Table 3 – An	nbient conditions key control characteristics	35
Table 4 – Ex	ternal magnetic field control characteristics	39

Table 6 – MOIF calibration protocol	45
Table 7 – Calibrated stray field measurement procedure	46
Table 8 – Uncertainty evaluation key control characteristics	52
Table A.1 – Sensor related artefacts and contingency strategies	63
Table A.2 – Imaging system and light source related artefacts and contingency strategies	63
Table B.1 – Product description and procurement information	64
Table C.1 – Product description and procurement information	67

INTERNATIONAL ELECTROTECHNICAL COMMISSION

NANOMANUFACTURING – KEY CONTROL CHARACTERISTICS –

Part 9-2: Nanomagnetic products – Magnetic field distribution: Magneto-optical indicator film technique

FOREWORD

- 1) The International Electrotechnical Commission (IEC) is a worldwide organization for standardization comprising all national electrotechnical committees (IEC National Committees). The object of IEC is to promote international co-operation on all questions concerning standardization in the electrical and electronic fields. To this end and in addition to other activities, IEC publishes International Standards, Technical Specifications, Technical Reports, Publicly Available Specifications (PAS) and Guides (hereafter referred to as "IEC Publication(s)"). Their preparation is entrusted to technical committees; any IEC National Committee interested in the subject dealt with may participate in this preparatory work. International, governmental and non-governmental organizations liaising with the IEC also participate in this preparation. IEC collaborates closely with the International Organization for Standardization (ISO) in accordance with conditions determined by agreement between the two organizations.
- 2) The formal decisions or agreements of IEC on technical matters express, as nearly as possible, an international consensus of opinion on the relevant subjects since each technical committee has representation from all interested IEC National Committees.
- 3) IEC Publications have the form of recommendations for international use and are accepted by IEC National Committees in that sense. While all reasonable efforts are made to ensure that the technical content of IEC Publications is accurate, IEC cannot be held responsible for the way in which they are used or for any misinterpretation by any end user.
- 4) In order to promote international uniformity, IEC National Committees undertake to apply IEC Publications transparently to the maximum extent possible in their national and regional publications. Any divergence between any IEC Publication and the corresponding national or regional publication shall be clearly indicated in the latter.
- 5) IEC itself does not provide any attestation of conformity. Independent certification bodies provide conformity assessment services and, in some areas, access to IEC marks of conformity. IEC is not responsible for any services carried out by independent certification bodies.
- 6) All users should ensure that they have the latest edition of this publication.
- 7) No liability shall attach to IEC or its directors, employees, servants or agents including individual experts and members of its technical committees and IEC National Committees for any personal injury, property damage or other damage of any nature whatsoever, whether direct or indirect, or for costs (including legal fees) and expenses arising out of the publication, use of, or reliance upon, this IEC Publication or any other IEC Publications.
- 8) Attention is drawn to the Normative references cited in this publication. Use of the referenced publications is indispensable for the correct application of this publication.
- 9) IEC draws attention to the possibility that the implementation of this document may involve the use of (a) patent(s). IEC takes no position concerning the evidence, validity or applicability of any claimed patent rights in respect thereof. As of the date of publication of this document, IEC had not received notice of (a) patent(s), which may be required to implement this document. However, implementers are cautioned that this may not represent the latest information, which may be obtained from the patent database available at https://patents.iec.ch. IEC shall not be held responsible for identifying any or all such patent rights.

IEC TS 62607-9-2 has been prepared by IEC technical committee 113: Nanotechnology for electrotechnical products and systems. It is a Technical Specification.

The text of this Technical Specification is based on the following documents:

Draft	Report on voting
113/817/DTS	113/830/RVDTS

Full information on the voting for its approval can be found in the report on voting indicated in the above table.

The language used for the development of this Technical Specification is English.

This document was drafted in accordance with ISO/IEC Directives, Part 2, and developed in accordance with ISO/IEC Directives, Part 1 and ISO/IEC Directives, IEC Supplement, available at www.iec.ch/members_experts/refdocs. The main document types developed by IEC are described in greater detail at www.iec.ch/publications.

A list of all parts in the IEC 62607 series, published under the general title *Nanomanufacturing – Key control characteristics*, can be found on the IEC website.

The committee has decided that the contents of this document will remain unchanged until the stability date indicated on the IEC website under webstore.iec.ch in the data related to the specific document. At this date, the document will be

- reconfirmed,
- withdrawn, or
- revised.

IMPORTANT – The "colour inside" logo on the cover page of this document indicates that it contains colours which are considered to be useful for the correct understanding of its contents. Users should therefore print this document using a colour printer.

IEC TS 62607-9-2:2024 © IEC 2024 – 9 –

INTRODUCTION

Measurements of magnetic fields that are homogeneous over macroscopic volumes can be made traceable to the SI standards. Traceable calibration chains from national metrology institutes to the end users are well-established.

However, many important industrial applications rely on precision sensing of spatially varying magnetic fields. End-users need traceably quantitative characterization tools for magnetic materials on the micrometre to centimetre scale to perform quality management of their production processes.

IEC TS 62607-9-1 [1]¹ established high-resolution magnetic field measurements based on calibrated magnetic force microscopy. While qMFM can be regarded as the gold standard for nanoscale magnetic field measurements with highest spatial resolution, its technical application is often hindered by several drawbacks: qMFM does not provide a high time resolution and it has a limited scan range (typically up to 100 μ m × 100 μ m in commercial systems). Also, qMFM can only deal with samples that are flat on a 100 nm scale. On the other hand, nuclear magnetic resonance (NMR) based SI standards can only be applied to centimetre scale macroscopic objects. However, industrially relevant magnetic materials often combine micrometre scale magnetic features with sample dimensions in the millimetre or centimetre range and rough rather than flat surfaces.

Magneto-optical sensor technology is already used in the testing of magnetic materials and partly also for quality control of magnetic components. Prominent examples for such industrial samples with high economic relevance and high production numbers are:

- Magnetic scales for the fabrication of precise magnetic encoders for length measurement systems and rotary encoders, e.g. for automotive applications; relevant parameters to be metrologically assessed, like magnetic period, pole location, magnetic pole length, or pole width, are, for example, defined in the DIN SPEC 91411 [2].
- High-quality electrical steel sheets (grain-oriented SiFe alloys), which are used in rotating machinery and generators for efficient power generation and in transformers for low-loss electrical energy conversion. While the relevant metrological parameters are for example discussed in DIN EN 10107 [3], magneto-optical testing allows the magnetic and loss properties to be related to the underlying grain and domain structure.

This document closes the length scale gap for magnetic field measurements by establishing a quantitative magneto-optical indicator film measurement technique (qMOIF) for magnetic field distribution. qMOIF is a fast (sub second resolution) imaging technique, that allows a one-shot characterization of samples with areas of several square centimetres and with a resolution down to the micrometre range. It can be used under room temperature conditions and for direct sample testing without the need for costly and time-consuming surface treatments. qMOIF allows a near-field testing of the distribution of the stray magnetic field directly at the specimen surface. However, without magnetic and geometric calibration as well as proper adjustment of the setup geometry, qMOIF merely delivers qualitative stray field images. This results from the fact that the measured signal depends on the properties of magneto-optical indicator film used as well as on the setup geometry and the detector.

¹ Numbers in square brackets refer to the Bibliography.

MOIF imaging can be used in two basic operation modes that enable feature analysis and the characterization of quantitative stray field distributions, respectively.

- a) The first mode, the "geometrical feature detection mode", allows the characterization of the density and characteristic dimension of certain magnetic features on the basis of a magneto-optical image. The contrast is adjusted to give maximum contrast of certain features compared to the background. It is for example used for a dichotomization of the surface into areas with two distinct characteristics, like up and down magnetized domains. This mode is, for example, used for a quantitative characterization of domain widths and areal percentage.
- b) The second mode, the "quantitative stray field distribution analysis mode", allows one to perform a spatially resolved analysis of the stray field distribution above the surface of a sample. This demands a magnetic calibration that includes the characterization of the sensor and the setup. Thereby quantitative values of key control characteristics (KCCs) like magnetic field amplitudes are made accessible and ultimately become traceable to national calibration standards.

This document aims at providing a description of the measurement approaches for both above defined modes. This includes the adjustment of the setup and the traceable calibration and thus feature analysis as well as traceably calibrated field distribution measurements.

In summary, this document provides a traceable method for spatially resolved and quantitative micrometre-resolution measurements of magnetic field patterns with centimetre image sizes which can be applied to technologically relevant materials with flat surfaces. Thereby, it will further advance the precise control of fabrication processes and final product qualification. The values of the key control characteristics for those products are very product specific (see, for example, IEC TS 62622:2012 [4]).

NANOMANUFACTURING – KEY CONTROL CHARACTERISTICS –

Part 9-2: Nanomagnetic products – Magnetic field distribution: Magneto-optical indicator film technique

1 Scope

This part of IEC 62607 establishes a standardized method to determine the key control characteristic

• magnetic field distribution

of nanomagnetic materials, structures and devices by the

• magneto-optical indicator film technique.

The magnetic field distribution is derived by utilizing a magneto optical indicator film, which is a thin film of magneto-optic material that is placed on the surface of an object exhibiting a spatially varying magnetic field distribution. The Faraday effect is then employed to measure the magnetic field strength by analysing the rotation of the polarization plane of light passing through the magneto-optic film.

- The method is applicable for measuring the stray field distribution of flat nanomagnetic materials, structures and devices.
- The method can especially be used to perform fast quantitative measurements of stray field distributions at the surface of an object.
- The magneto-optic indicator film technique is a fast, non-destructive method, making it an attractive option for materials analysis and testing in the industry.
- MOIF measurements can be done without any sample preparation and do not rely on specific surface properties of the object. It can be applied to the characterization of rough samples as well as of samples with non-magnetic cover layers.
- MOIF can quantitatively measure magnetic field distributions.
 - with a one-shot measurement which typically takes a few seconds
 - over areas of several square centimetres (over diameters of up to 15 cm with special techniques)
 - in a field range from 1 mT to more than 100 mT
 - with down to 1 µm spatial resolution
- Although techniques with nano-scale resolution are suitable for analysing the details of magnetic field structure, their ability to characterize larger areas is limited by their scanning area. Therefore, the MOIF technique is an indispensable complementary method that can offer a more comprehensive understanding of material properties.

This document focuses on the calibration procedures, calibrated measurement process, and evaluation of measurement uncertainty to ensure the traceability of quantitative magnetic field measurements obtained through the magneto-optic indicator film technique.

2 Normative references

There are no normative references in this document.